Creative Computing II

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Autumn 2010, Wednesdays: 10:00–12:00: RHB307 & 14:00–16:00: WB316 Winter 2011, TBC

- anima, Latin: soul or mind;
- cognates: Greek anemos: wind; Sanskrit aniti breathes.
- "to bring to life"; "making things move"
- component of computer graphics:
 - realtime constraints for interactive media (e.g. games);

offline (non-realtime) rendering for film.

Two distinct approaches to computer animation:

- Physical modelling
 - Describe situation in (simplified) physical terms;
 - Simulate solution to equations of motion:
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 - Describe situation in (simplified) physical terms;
 - Simulate solution to equations of motion:
 - Use simulation to place animated objects appropriately.
- Keyframing
 - Specify positions of animated objects at particular times;
 - Interpolate between specified position to achieve desired smoothness.

Given equation of motion:

$$\ddot{\mathbf{x}}_i = \frac{\mathsf{d}^2 \mathbf{x}_i}{\mathsf{d}t^2} = f_i(\mathbf{x})$$

Solution is:

$$\begin{aligned} \mathbf{x}_i(t+\delta t) &= \mathbf{x}_i(t) + \dot{\mathbf{x}}_i(t)\delta t; \\ \dot{\mathbf{x}}_i(t+\delta t) &= \dot{\mathbf{x}}_i(t) + f_i(\mathbf{x})\delta t. \end{aligned}$$

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So given starting positions $\mathbf{x}(t_0)$ and velocities $\dot{\mathbf{x}}(t_0)$, we can evolve the physical model forwards (and backwards) in time.

Observations:

- $f_i(\mathbf{x})$ may be difficult to derive;
- even once derived, $f_i(\mathbf{x})$ may be difficult to compute;
- what if we want to specify initial and final positions?

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- even once derived, $f_i(\mathbf{x})$ may be difficult to compute;
- what if we want to specify initial and final positions?
- difficult to handle agency in this framework;
 - what is the brain's equation of motion?
- suitable for:
 - visualisation of simulations (particle systems, physics, "artificial life");

animation of very simple situations.

Animation Keyframing

the frame where an object's position is specified is a 'key frame' for that object;

- $\blacktriangleright \mathbf{x}_i(t_k) = \mathbf{x}_i^{(k)}$
- how to decide suitable times and positions?
 - rôle of the *lead animator*;
 - data-driven approach (motion capture).

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 - data-driven approach (motion capture).
- interpolation:
 - traditionally: frames in between filled in by assistant animators;
 - computationally: generate a suitable path for object between key frames;

'in-betweening' or 'tweening'.

Animation Flip Books

- Fundamental method of animation;
- Existed in Victorian era;
- Present a sequence of pictures in rapid succession:
 - smooth motion illusion for small differences between pictures.

 Animation on modern displays (TV, cinema, computers) is essentially a flip book.

Cel Animation

- Similar to flip books;
- Each frame is an image, drawn individually;

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- Layering:
 - Distinguish between objects and background:
 - Use a single non-animated image for the background;

- Use transparent layers for animated objects;
- Camera motion can still pan over the background.

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 - For slow motion, only generate half as many new object positions;
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- Animation Loops:
 - Suitable for repetitive motion (*e.g.* walking);
 - Easily-detected, can be distracting.

Animation Cel Animation

Animation Loop:



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Animation Loop:



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Stop-motion Animation

Basic workflow:

- Create models of scene and characters;
- Pose, take a photo;
- Move slightly, take a photo;
- Lather, rinse, repeat.

Observations:

- Huge effort in initial creation;
- Each individual frame is not much extra work;

Very time-consuming.

Animation Stop-motion Animation

Modern computer animation is quite similar to traditional stop-motion animation:

 Generate a computational (virtual) model of scene and characters;

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- Generate a computational (virtual) model of scene and characters;
- Animate by moving the characters frame-by-frame:
 - character has multiple control points (joints on a 'skeleton');

- move control points quasi-independently;
- 'rigging' a character.

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- Animate by moving the characters frame-by-frame:
 - character has multiple control points (joints on a 'skeleton');

- move control points quasi-independently;
- 'rigging' a character.
- Generating successive frames is easy.

In computer animation context, keyframing is a labour-saving device:

animator specifies positions of control points at suitable times;

• *computer* performs in-betweening.

In computer animation context, keyframing is a labour-saving device:

animator specifies positions of control points at suitable times;

- computer performs in-betweening.
- ► Note:
 - key frame is not an image
 - cf. key frames in cel animation
- in-betweening by interpolation
 - linear interpolation;
 - splines (Bézier curves, Hermite polynomials).

Interpolation

Linear interpolation between (\mathbf{x}_0, t_0) and (\mathbf{x}_1, t_1) :

- at time t₀, position is x₀;
- at time t₁, position is x₁;
- in between those times, position is
 - on the line joining x₀ and x₁;
 - appropriate for motion at a constant velocity;

(so position is a linear function of time).

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So for $t_0 \leq t \leq t_1$

$$\mathbf{x}(t) = \mathbf{x}_0 + \frac{\mathbf{x}_1 - \mathbf{x}_0}{t_1 - t_0}(t - t_0)$$

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Observations:

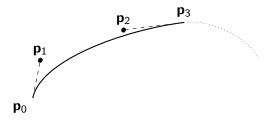
- Motion during interpolation is smooth;
- Jerkiness at change between interpolated segments.

Interpolation

Cubic Bézier curves: for each segment, specify

- two curve end points p₀, p₃;
- two control points p₁, p₂;

▶ for
$$0 \le t \le 1$$
:
 $\mathbf{x}(t) = (1-t)^3 \mathbf{p}_0 + 3t(1-t)^2 \mathbf{p}_1 + 3t^2(1-t)\mathbf{p}_2 + t^3 \mathbf{p}_3$.



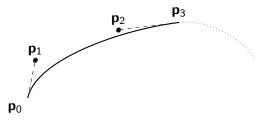
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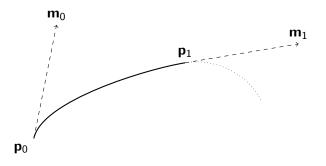


- smooth curve;
- does not go through control points.

Interpolation

Cubic Hermite curves: for each segment, specify

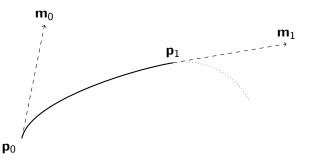
- two curve end points p₀, p₁;
- tangents at those end points m₀, m₁;
- ► for $0 \le t \le 1$: $\mathbf{x}(t) = (2t^3 3t^2 + 1)\mathbf{p}_0 + (t^3 2t^2 + t)\mathbf{m}_0 + (-2t^3 + 3t^2)\mathbf{p}_1 + (t^3 t^2)\mathbf{m}_1$



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- smooth curve;
- choose tangents automatically.

Interpolation

Catmull-Rom splines:

- Hermite curves;
- Tangents chosen as half the distance between surrounding keyframes:

$$\blacktriangleright \mathbf{m}_k = \frac{\mathbf{p}_{k+1} - \mathbf{p}_{k-1}}{2}$$

- Smooth motion over multiple segments;
- Zero-tangents at first and last keyframe give 'slow-in slow-out' behaviour.